



Precision Horticulture Lab

College of Agricultural & Environmental Sciences

UNIVERSITY OF GEORGIA

PLANT COUNTS

DIAMETER (CM)

Using Artificial Intelligence (AI) and Drones (UAVs) to Estimate Onion Bulb Counts and Market Sizes

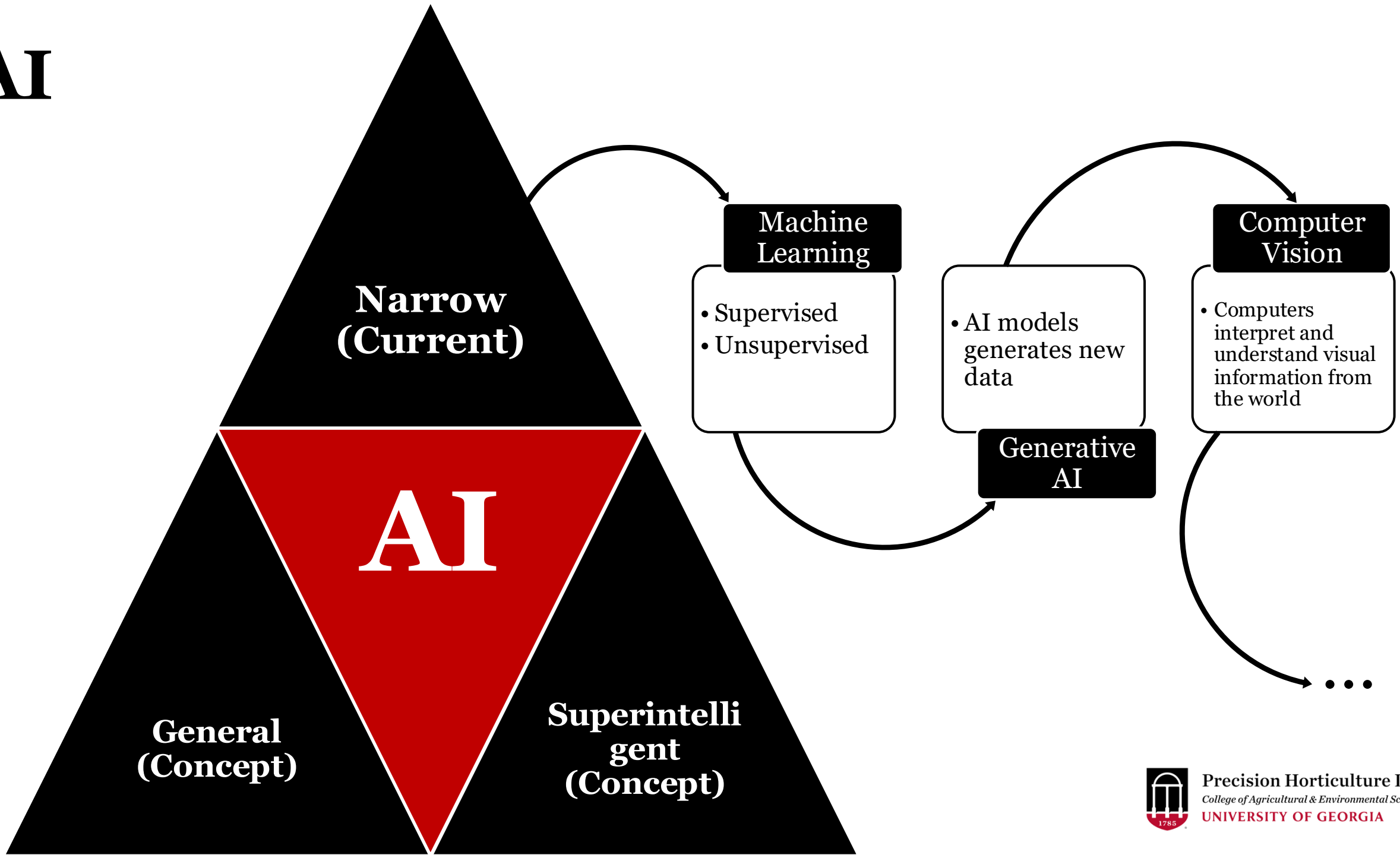
1%	197
15%	2,246
74%	10,967
10%	1,408



Dr. Luan Pereira de Oliveira, Victor Martins M.S., Dr. Marcelo Barbosa, Regimar dos Santos M.S., Lucas Sales, M.S., and



AI



Narrow AI in Agriculture

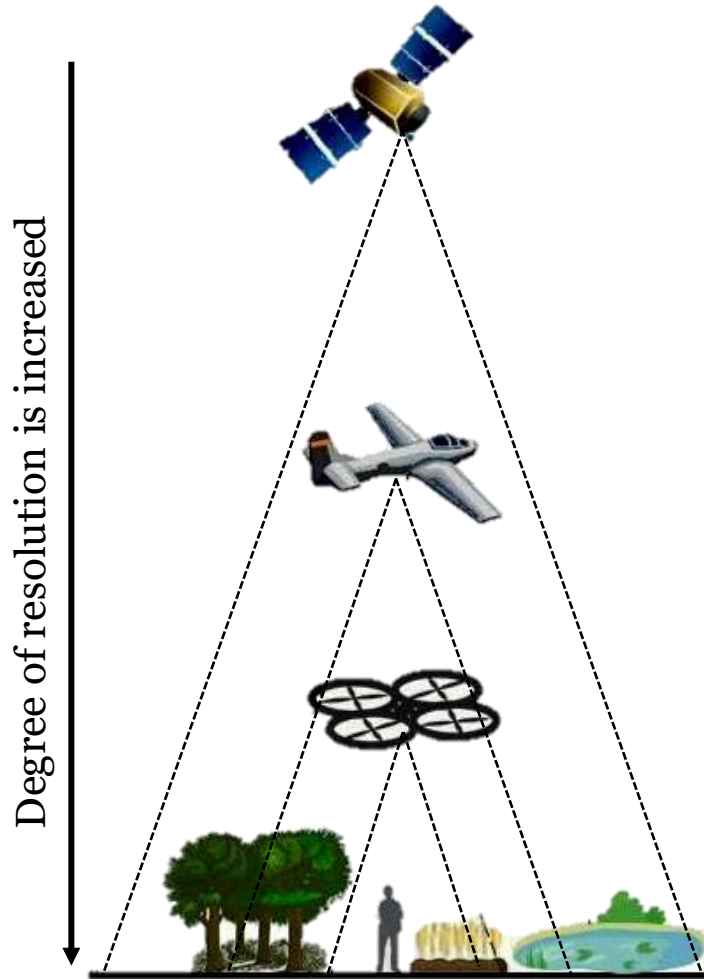
Robotics and automated machinery: *AI enables unmanned ground vehicles that can take in-site decisions on where to mechanically remove weeds, spray, and harvest crops.*

Crop and soil monitoring: *AI algorithms analyze data from sensors (satellites and drones) to predict crop yields, detect plant diseases, and prescribe effective control methods.*

Predictive analytics: *AI tools forecast environmental impacts, crop productivity, and market conditions.*



Remote Sensing



RGB
(Red, Green, Blue)



Multispectral
(Red, Green, Blue,
NIR, and Red Edge)



Hyperspectral
(Multispec. +)



Thermal

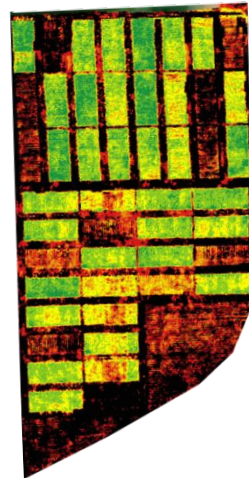


Remote/Proximal Sensing

Approaches to identify issues and variability within a field or sampling set

- Spectral Response
- Identification and Segmentation of Objects

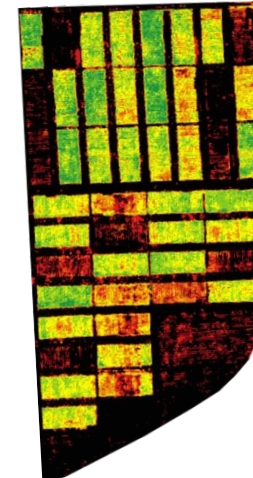
NDVI



$$\frac{\text{NIR} - \text{RED}}{\text{NIR} + \text{RED}}$$

$$\text{NIR} + \text{RED}$$

NDRE



$$\frac{\text{NIR} - \text{R.E}}{\text{NIR} + \text{R.E}}$$

$$\text{NIR} + \text{R.E}$$



“Hard Mode”

Vs

“Easy Mode”

Digital Ag Tech



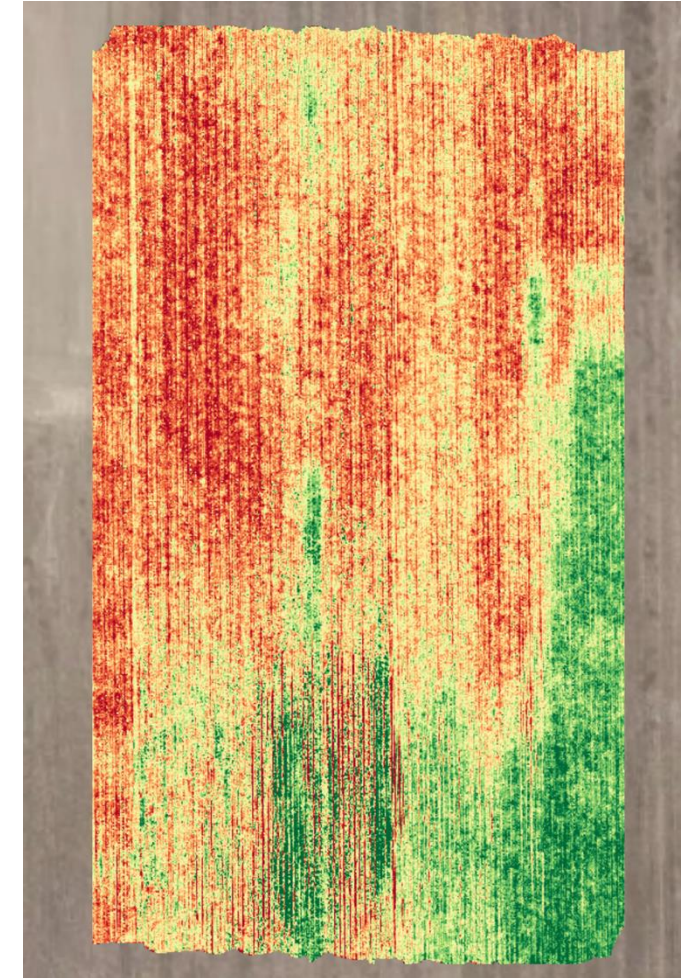
+ AI =



Manual “Hard” Mode

Phyton, R, SAS, Metashape, etc...

```
async def run():  
  
    """ Does Offboard control using attitude commands. """  
  
    drone = System(mavsdk_server_address='localhost', port=50051)  
    await drone.connect(system_address="udp://:14540")  
  
    print("Waiting for drone to connect...")  
    async for state in drone.core.connection_state():  
        if state.is_connected:  
            print(f"-- Connected to drone!")  
            break  
  
    print("Waiting for drone to have a global position estimate...")  
    async for health in drone.telemetry.health():  
        if health.is_global_position_ok and health.is_home_position_ok:  
            print("-- Global position estimate OK")  
            break
```



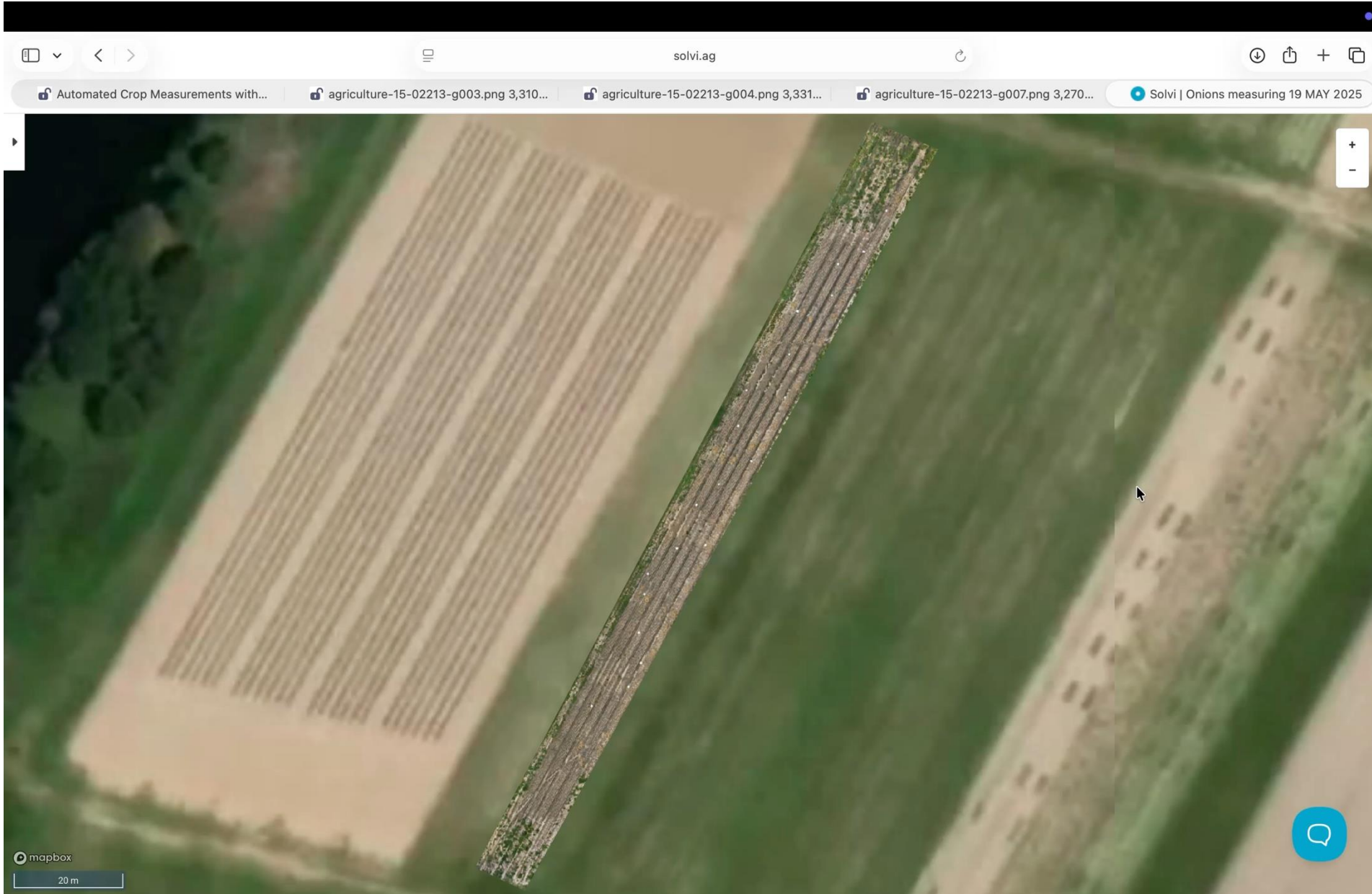
Manual “Hard” Mode

The screenshot displays the RStudio environment with the following components:

- Source Editor:** Contains R code for image processing and analysis. Key steps include:
 - Defining `image_folder` and `image_files`.
 - Listing files and creating `all_data`.
 - Reading images into a `raster` object and plotting RGB channels.
 - Using `fieldIndex` to identify features and plotting the results.
 - Applying a `mask` and `fieldCount` to analyze the image.
 - Calculating `circularity` for the identified features.
 - Cropping the image based on the identified features and plotting the results.
 - Extracting R, G, and B values for the cropped image and creating a data frame.
- Console:** Shows the output of the code, including the message `[1] "3 layers available"`.
- Environment:** Shows the loaded objects and their attributes.
- Viewer:** Displays the final image, which is a grayscale image of a plant with a 4x4 grid of black dots overlaid. A yellow sticky note with the number "1" is placed below the grid.



AI-driven “Easy” Mode



Is it possible to count and measure Onions with Drones and AI?

Open Access Article

Automated Crop Measurements with UAVs: Evaluation of an AI-Driven Platform for Counting and Biometric Analysis

by João Victor da Silva Martins ^{1,2,*}  , Marcelo Rodrigues Barbosa Júnior ¹  ,
Lucas de Azevedo Sales ¹ , Regimar Garcia dos Santos ¹ , Wellington Souto Ribeiro ²   and
Luan Pereira de Oliveira ^{1,*}  

¹ Department of Horticulture, University of Georgia, Tifton, GA 31793, USA

² Department of Agronomy, Federal University of Viçosa, Viçosa 36570-900, MG, Brazil

* Authors to whom correspondence should be addressed.

Agriculture **2025**, *15*(21), 2213; <https://doi.org/10.3390/agriculture15212213>

Submission received: 16 September 2025 / Revised: 21 October 2025 / Accepted: 22 October 2025 /

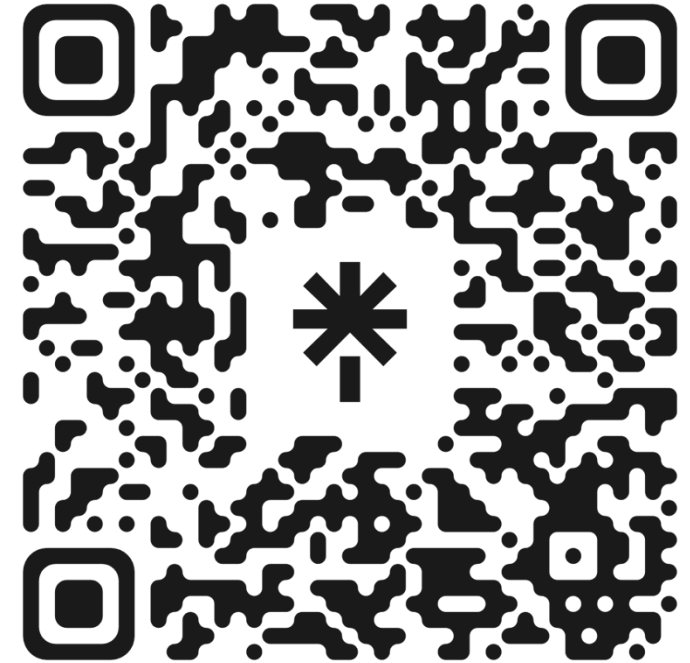
Published: 24 October 2025

(This article belongs to the Special Issue Image Analysis Techniques in Quality Assessment of Agricultural Products)

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Browse Figures

Versions Notes



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Objectives

- To evaluate the performance of a commercial AI-powered digital agriculture web platform (Solvi) for automated biometric analysis in specialty crops (pecan and onion) using (Drone) UAV-acquired imagery.
- To verify the accuracy and precision of onion counting after undercutting
- To verify the potential of onion classification into USDA market sizes.
- To explore the possibility of predicting yield based on the data.



Material and Methods



- Vidalia Onion Research and Education Center, Lyons, GA
- DJI Mavic 3M
- RGB Img
- 30ft
- 0.13in/px
- 75% overlapping



0.13 inch

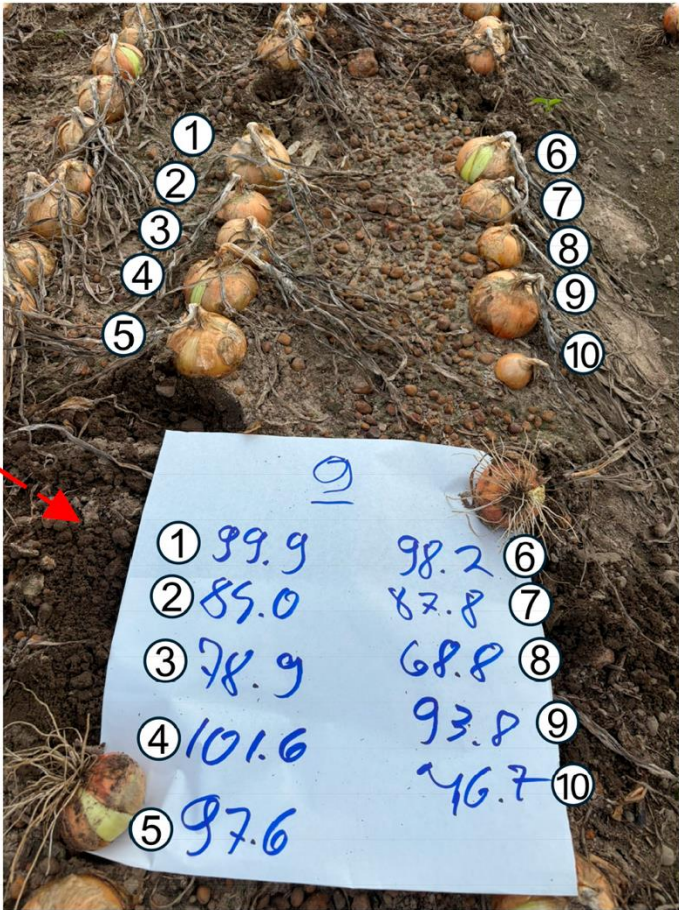


Material and Methods

Orthomosaic



Sample point (ID 9)



Data classification

ID	Diameter (mm)	Class
1	99.9	Colossal
2	85.0	Jumbo
3	78.9	Jumbo
4	101.6	Colossal
5	97.6	Colossal
6	98.2	Colossal
7	87.8	Jumbo
8	68.8	Medium
9	93.8	Jumbo
10	46.7	Medium



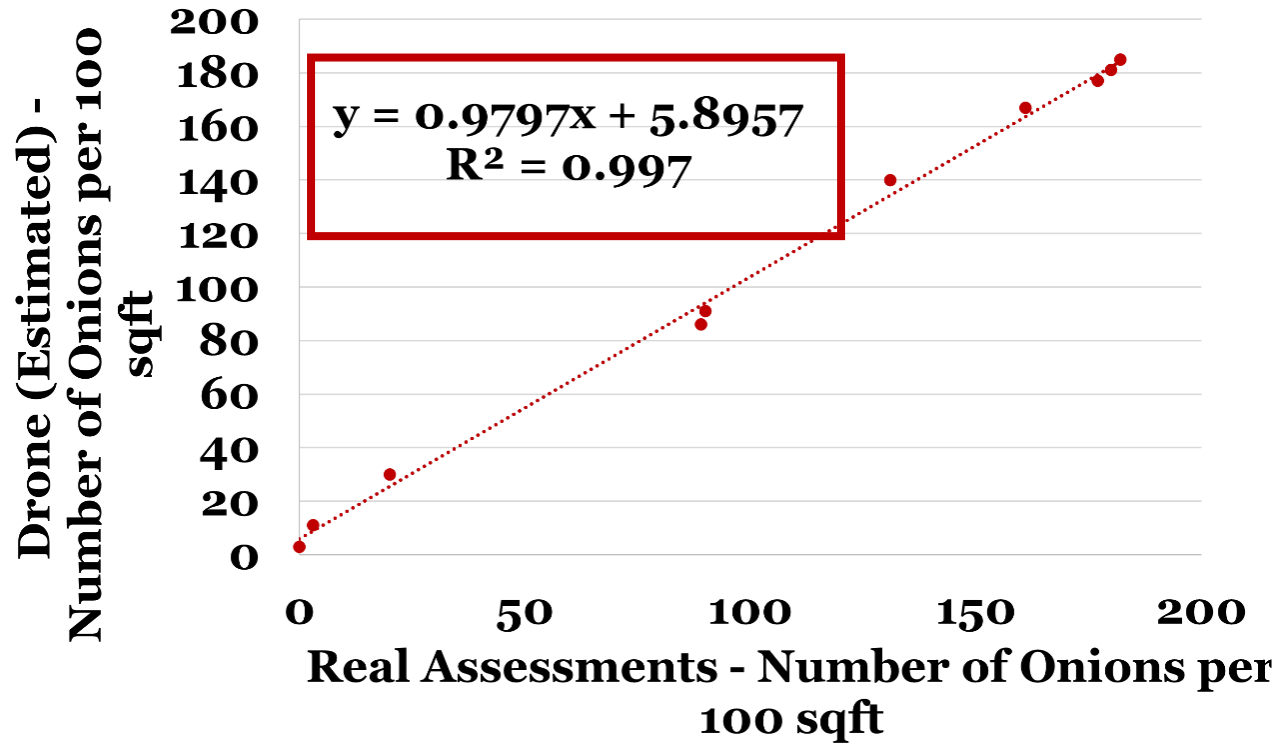
Material and Methods



- Total Number of Onions
- Number of True Positives (Proper measurements)
- Number of False Positives (Other objects counted as onions)
- Number of True Negatives (Objects that were not counted as onions)
- Number of False Negatives (Onions not counted)



Results - Counts



$$\text{Precision} = \frac{\text{True Positives}}{\text{False Positives} + \text{False Negatives}}$$

$$\text{Recall} = \frac{\text{True Positives}}{\text{True Positives} + \text{False Negatives}}$$

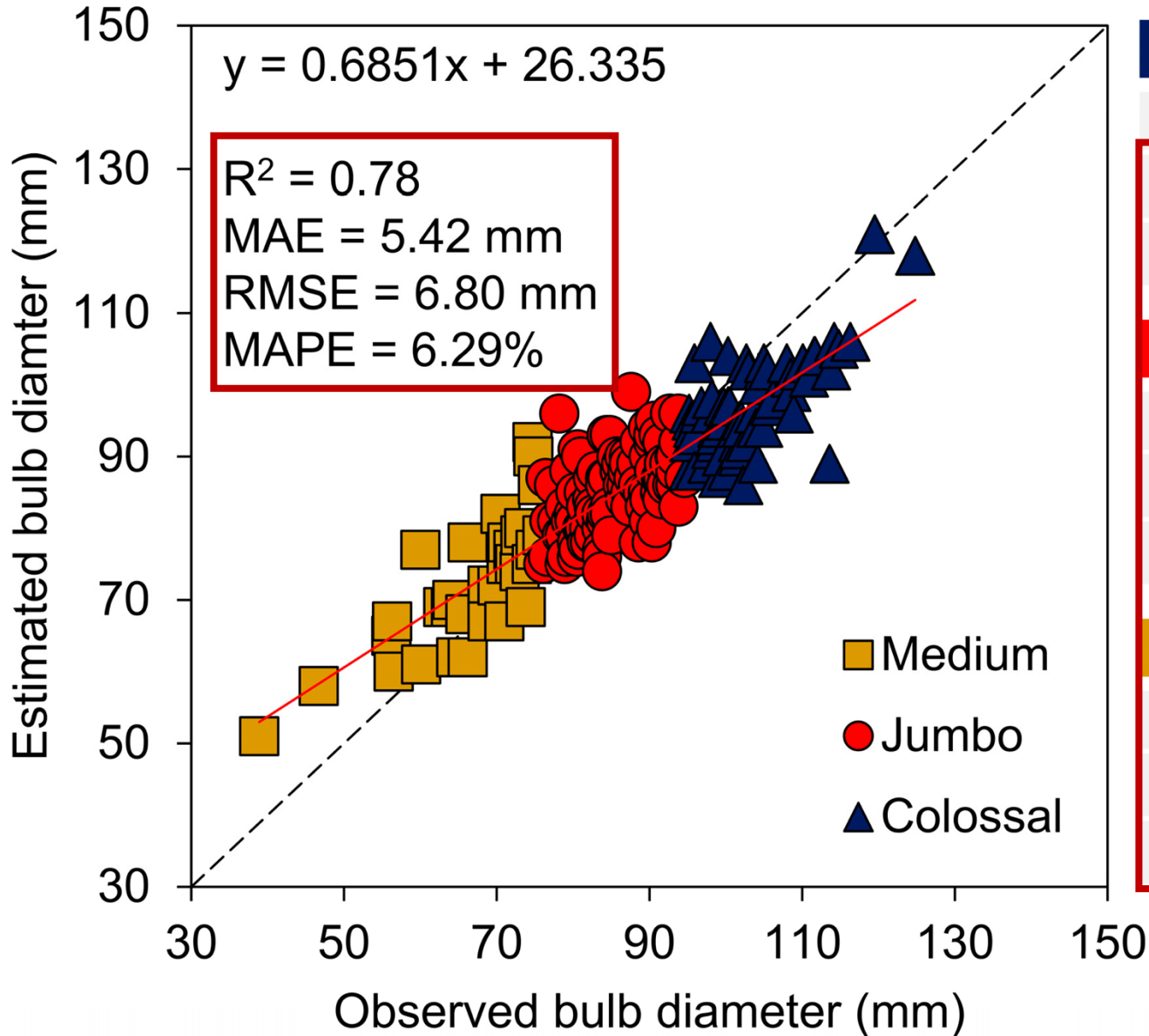
$$\text{F1 Score} = 2 \times \frac{\text{Precision} + \text{Recall}}{\text{Precision} \times \text{Recall}}$$

Table 2. Onion counting analysis results.

Metric	Value
Precision	0.985
Recall	0.970
F1 Score	0.978



Results - Size



Colossal			
$y = 0.694x + 25.403$			
R^2	MAE	RMSE	MAPE
0.45	6.92 mm	8.21 mm	6.62%
Jumbo			
$y = 0.5608x + 36.997$			
R^2	MAE	RMSE	MAPE
0.25	4.20 mm	5.31 mm	4.90%
Medium			
$y = 0.8166x + 17.54$			
R^2	MAE	RMSE	MAPE
0.60	6.32 mm	7.86 mm	9.99%

Results - Size

- (b) Size Requirements - Provided that unless otherwise specified, size shall be specified in connection with the grade in terms of one of the size classifications listed below:
1. "Small" shall be from 1 to 2 1/4 inches in diameter.
 2. "Medium" shall be from 2 to 3 1/4 inches in diameter.
 3. "Large Medium" shall be 2 1/2 inches or larger in diameter.
 4. "Large" or "Jumbo" shall be 3 inches or larger in diameter.
 5. "Colossal" shall be 3 3/4 inches or larger in diameter.

Source: <https://rules.sos.state.ga.us/gac/40-7-8#:~:text=5.,inches%20or%20larger%20in%20diameter.&text=Tolerances%20for%20size:%20In%20order,than%20the%20maximum%20diameter%20specified.&text=Special%20Purpose%20Shipments:,set%20forth%20in%20this%20section.>

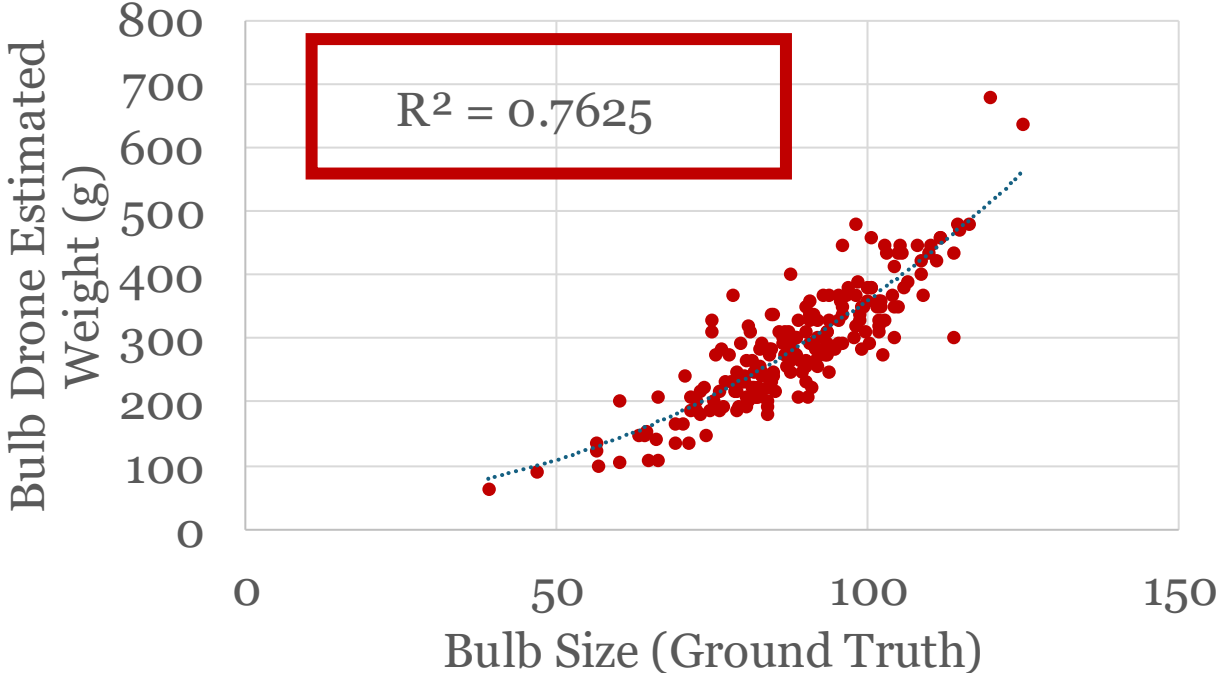
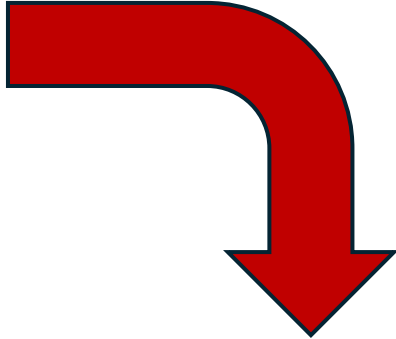
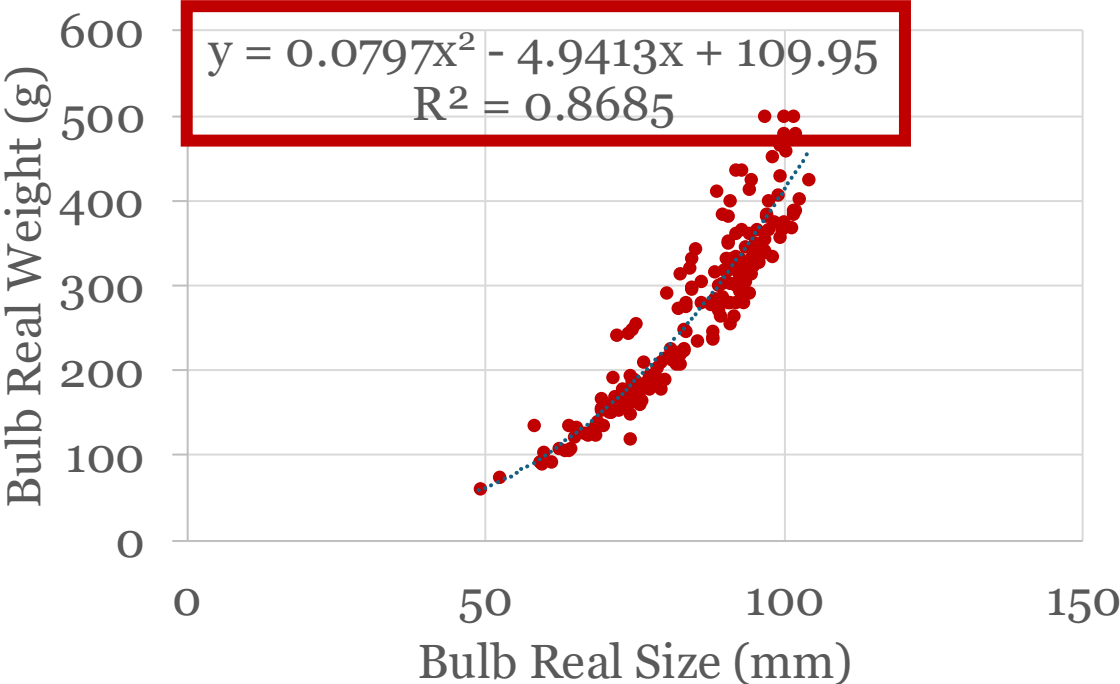


Conclusions

- The AI-powered web platform showed **good accuracy in estimating onion biometric traits**, particularly **bulb diameter**, when compared with ground-truth measurements.
- The results support the **use of cloud-based AI tools for automated morphological measurements** in onion production systems under real field conditions.
- Future work** should validate performance across additional **phenological stages, production environments, and onion cultivars**.
- Further expansion could include **yield and quality prediction models** specifically tailored for onions.
- The platform may also benefit from integrating **additional sensing technologies**—such as ground-based robotics—to improve **scalability, resolution, and early-season measurement accuracy**.



Next Steps – Predicting Yield – Preliminary



Thanks!



luan@uga.edu



luan.agro



linkedin.com/in/luan-agro

Special Thanks...



Vidalia Onion and
Vegetable Research Center
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